Functions

Input independent variable(s), output dependent variable(s).

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Vector-Valued Function

Consider the line: $ec{r}(t) = egin{bmatrix} 1+2t \ 5t \ 8-3t \end{bmatrix}$, $t\in\mathbb{R}$

- vector-valued function 1 input, 3 outputs
- \blacktriangleright parameter t
- output is the "position" at the given "time"
- make a table
- describes a dynamic path
- parametric equations for each coordinate
- what if restrict domain to $t \in [0, 2]$?

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Swinging Arm Multi-variable Intro

- ▶ area table vs formula $A(a, b) = \frac{1}{3}b^{3/2}a^{-1/2}$
- a and b are independent variables/parameters (dials)
- \blacktriangleright A depends on a and b
- domain $b \leq 36a$
- range $A \ge 0$
- partial derivatives ^{∂A}/_{∂a} and ^{∂A}/_{∂b}
 are ratios of change in A
 to changes in a or b respectively
 A(2,02,07,86) = A(2,28) + ^{∂A}/_∂A = + ^{∂A}/_∂A
- $\blacktriangleright A(2.03, 27.86) \approx A(2, 28) + \frac{\partial A}{\partial a} \Delta a + \frac{\partial A}{\partial b} \Delta b$

Distance to Hospital

- city boundary $[0, 10] \times [-3, 5]$
- ▶ hospital at H(2,0)
- $\blacktriangleright D(x,y) = \sqrt{(x-2)^2 + y^2}$
- find the range
- visualize as a surface: a cone
- "squared distance": a paraboloid

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Multi-Variable Function

Consider the plane:

- $z(x,y) = 5 + 2x + 7(y-3), \, (x,y) \in \mathbb{R}^2$
- multi-variable function 2 inputs, 1 output
- given x, y location, gives the "elevation"
- make a table
- describes a surface
- ▶ sketch region where x, y, z are all ≥ 0

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Domain/Range



independent variable(s): inputs
dependent variable(s): outputs
domain: set of possible inputs
range: set of possible outputs

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Non-flat Examples

- 1. An object follows a sine curve from (0,0)when t = 0 to (2,1) when t = 5. Make a table. Find parametric equations for x and y.
- 2. Sketch surface $z = f(x, y) = 36 4x^2 y^2$, such that $z \ge 0$. What do the cross-sections look like ?

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Functions

Visualizing

vector-valued function

- trajectory of an object moving in space
- separate parametric equations (x(t), y(t), z(t)) can be plotted with respect to t
- multi-variable function
 - surface plot
 - contours
 - heat map

Also, a table of values may be more insightful than a formula, which might not be available.

Contours

A contour, (level or iso curve) is the solution set of f(x, y) = c, for a constant c.

- weather iso-bars (barometric pressure), or iso-therms
- topographical maps
- walk along contour elevation constant
- contours corresponding to distinct levels cannot cross
- contrast contours of a cone and a paraboloid

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More Examples



- 1. $\vec{r}(t) = [\cos(t); \sin(t); t], t \in [0, \infty)$
- 2. Predator-prey (e.g. wolf-rabbit) state space path; somewhat cyclical, but chaotic.
- 3. $P(r,m) = \frac{1000r/12}{1-(1+r/12)^{-m}}$ (monthly car payment if borrow 1000 dollars at annual rate r for m months)

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Surfaces

- The graph of an equation is the set of points that satisfy it.
- in \mathbb{R}^2 , graph the "curves" $y = 1, y = x, y = x^2, x^2 + y^2 = 1$
- ▶ in \mathbb{R}^3 , graph the surfaces:

$$z = 1$$

$$3x + 4y + z = 2$$

$$z = x + y$$

$$z = \sqrt{x^2 + y^2}$$

$$x^2 + y^2 + z^2 = 1$$

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Multivariable Function Examples

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Examples

Find domain, range, and contours. Visualize surface with software.

2

1.
$$z(x, y) = \sqrt{36 - 4x^2 - 9y}$$

2. $z = \sqrt{x^2 + y^2}$
3. $z = \ln(xy)$
4. $z = x^2 - y^2$
5. $f(x, y) = e^{-x^2y}$
6. $f(x, y) = \frac{3x - y}{x^2 + 2y^2 + 1}$

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Economics

"indifference curves" represent constant utility (benefit,enjoyment) if trade-offs can be made





Definition 1

If |f(x, y) - L| can be made arbitrarily small by chosing (x, y) "close" enough to (a, b), then:

$$\lim_{x,y \to a,b} f(x,y) = L$$

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Continuity

Definition 2

$$f ext{ is continuous at } (a,b) ext{ if } \ \lim_{x,y o a,b} f(x,y) = f(a,b)$$

Polynomials, rational, trig, logs, exponential functions are continuous on their domains. So just plug in to find the limit. For example, $z = \ln(x + y^2)$ is



continuous on the domain $x > -y^2$.

Approach



For the limit to exist, the answer must be the same no matter how you approach.

- In functions of one variable, can approach from left or right.
- If multi-variable, then can approach from infinitely many directions and paths.

Approach

Use polar coordinates to investigate these limits.

$$\begin{array}{l} 1. \quad \lim_{x,y \to 0,0} \frac{x^3}{x^2 + y^2} = \lim_{r \to 0} r \cos^3(\theta) = 0 \\ 2. \quad \lim_{x,y \to 0,0} \frac{xy}{x^2 + y^2} \\ 3. \quad \lim_{x,y \to 0,0} \frac{xy^2}{x^2 + y^4} \end{array} \end{array}$$

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Multivariable Functions

GOF

$$g(x,y)=rac{1}{1+e^{-u}} \qquad u=rac{x-y}{2\sqrt{x+y}}$$

x	y	u	g
10	0	1.58	.83
50	40	.53	.63
31	30	.06	.52
42	3	2.91	.95
49	3	3.19	.96
81	0	4.50	.99

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Rate of Change

Temperature function grid:

4	46	47	44	46	50
3	33	34	36	37	41
2	26	27	29	30	31
1	23	22	24	25	27
0	22	21	20	21	24
$egin{array}{c} y & \ x \end{array}$	0	1	2	3	4

▶ slope in W-E direction f_x(2,2) ≈ 30-27/(3-1) = 1.5
 ▶ slope in S-N direction f_y(2,2) ≈ 36-24/(3-1) = 6
 ▶ slope in NE direction? (rise over run)

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Definition 3 Given z = f(x, y), let $h = \Delta x$. The (finite) difference quotient w.r.t. xcentered $rac{\Delta z}{\Delta z} = rac{f(x+rac{1}{2}h,y) - f(x-rac{1}{2}h,y)}{2}$ $\Delta x =$ h. forward $rac{\Delta z}{\Delta z} = rac{f(x+h,y) - \overline{f(x,y)}}{2}$ Λx h.

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Definition 4

If the limit exists, the partial derivative of f w.r.t. x is denoted $f = \frac{\partial f}{\partial f} = \frac{\partial}{\partial f} f = D f = \lim_{x \to x} \frac{f(x+h, y) - f(x, y)}{f(x+h, y) - f(x, y)}$

$$f_x = rac{\partial f}{\partial x} = rac{\partial}{\partial x}f = D_x f = \lim_{h o 0} rac{f(w + h, g) - f(w, g)}{h}$$

all but one indep variable held constant

- slope of surface as you move parallel to axis
- instantaneous rate of change $\frac{\Delta z}{\Delta x} \approx \frac{\partial z}{\partial x}$
- ▶ given contour plot, which bigger $|f_x|$ or $|f_y|$?



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Calculating Partial Derivatives

- 1. $\frac{d}{dx}(x^2+1)^4$ 2. $\frac{d}{dx}(x^2+2)^4$ 3. $\frac{d}{dx}(x^2+3)^4$ 4. $\frac{d}{dx}(x^2-1)^4$ 5. $\frac{\partial}{\partial x}(x^2+y)^4$ 6. $\frac{\partial}{\partial x}(x^2+\cos(y))^4$
- Differentiate w.r.t. one variable; treat all others as constants.
- Use derivative rules (power, product, chain, etc).

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Examples

1.
$$z = f(x, y) = \sqrt{3x^2 + e^y}$$
; at the pt (1,0,2)

- Estimate $\frac{\partial z}{\partial x} \approx \frac{\Delta z}{\Delta x}$ using nearby points and the difference quotient.
- Estimate $\frac{\partial z}{\partial y}(\overline{1,0}) = \left. \frac{\partial z}{\partial y} \right|_{(1,0)}$
- Use derivative rules to find the partial derivative functions.
- Find partial derivatives of z = 3x²y + ^y/_x + y⁴.
 [∂]/_{∂y} [y²(e^x + x²y)³]

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Tangent Plane

Suppose f(5,8) = 40 and $\nabla f(5,8) = [7,3]$. \blacktriangleright point (5,8,40) \blacktriangleright normal vector $\begin{bmatrix} 1\\0\\f_x \end{bmatrix} \times \begin{bmatrix} 0\\1\\f_y \end{bmatrix} = \begin{bmatrix} -7\\-3\\1 \end{bmatrix}$ The tangent plane or "linearization" is

The tangent plane or "linearization" is -7(x-5) - 3(y-8) + 1(z-40) = 0or rearranging: z = 40 + 7(x-5) + 3(y-8)

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Tangent Plane

- Follow the same pattern for functions with more than one independent variable.
- ▶ $f(x, y) = x^2 y^3$, $\nabla f(x, y) = [2xy^3, 3x^2y^2]$ at (3, 1, 9), slopes $\nabla f(3, 1) = [6, 27]$, tangent plane z = 9 + 6(x - 3) + 27(y - 1)
- Zoom in enough, and the tangent plane is indistinguishable from the graph's surface.

Differentials

- Intuitively, f(x, y) is differentiable at a pt. if, as you zoom in, the surface becomes flat and coincides with the tangent plane.
- Theorem: if f(x, y) is 1st order smooth, then it is differentiable.
- increment: actual change $\Delta z = f(x + \Delta x, y + \Delta y) f(x, y)$
- ► differential: approximate change using tangent plane as proxy $dx = \Delta x, dy = \Delta y$ $dz = \frac{\partial z}{\partial x} dx + \frac{\partial z}{\partial y} dy$

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Linearization

The linearization of f at (x_0, y_0) is equal to the starting function value plus the differential.

$$egin{array}{rcl} \ell(x,y) &=& f(x_0,y_0) + f_x(x_0,y_0)(x-x_0) \ &&+ f_y(x_0,y_0)(y-y_0) \ &=& f(x_0,y_0) +
abla f(x_0,y_0) +
abla f(x_0,y_0) + egin{array}{rcl} \Delta x \ \Delta y \end{bmatrix} \ &=& f(x_0,y_0) + dz \end{array}$$

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Example

Consider $f(x, y) = x^2 y$ at (3, 2).

- Contour at (3,2) also passes thru (x,50).
- ▶ f(3,2) = 18 and $\nabla f(3,2) = [12,9]$
- ► linearization (tangent plane) z = 18 + 12(x - 3) + 9(y - 2)
- differential

dz = 12 dx + 9 dy

- ▶ Small move to (3.04, 1.97)
 - ▶ dz = 12(.04) + 9(-.03) = .21
 - ► $\Delta z = f(3.04, 1.97) f(3, 2) = .20595$
 - ► $f(3.04, 1.97) \approx \ell(3.04, 1.97) = 18.21$

Preserved Information

Suppose the plane z = 7 - 3(x+4) + 5(y-2) is tangent to f(x, y).

- 1. Point of tangency (-4, 2, 7).
- 2. Normal vector $\vec{n} = [-3; 5; -1]$
- 3. Gradient $\nabla f(-4,2) = \begin{bmatrix} -3\\5 \end{bmatrix}$.
- 4. Normal line $\ell(t) = \begin{bmatrix} -4\\2\\7 \end{bmatrix} + \begin{bmatrix} -3\\5\\-1 \end{bmatrix} t$
- 5. Estimate f(-4.13, 2.04) $\approx 7 - 3(-.13) + 5(.04) = 7.59$

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Consider the paraboloid $f(x, y) = 1 + x^2 + 4y^2$.

- 1. point on surface P(3, 1, z)
- 2. find gradient
- 3. find the linearization of f
- 4. find line thru P normal to surface
- 5. where would it puncture the surface again? at what angle ?

Directional Derivative

Given gradient: slope if you walk E,W,N,S,NE ?



Multiv

If z differentiable, use tangent plane to find slope in direction of $\vec{v} = \begin{bmatrix} dx \\ dy \end{bmatrix}$.

$$D_{ec v} z = rac{ ext{rise}}{ ext{run}} = rac{dz}{\|ec v\|} = rac{
abla z \cdot ec v}{\|ec v\|}$$

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Multivariable Functions

Derivatives of Derivatives

$$f(x, y) = 7x^{3}y + \frac{5}{y}$$
stradient vector
$$\nabla f = \begin{bmatrix} \frac{\partial f}{\partial x} \\ \frac{\partial f}{\partial y} \end{bmatrix} = \begin{bmatrix} f_{x} \\ f_{y} \end{bmatrix} = \begin{bmatrix} 21x^{2}y \\ 7x^{3} - 5y^{-2} \end{bmatrix}$$
Hessian matrix $H = \begin{bmatrix} \frac{\partial}{\partial x} \left(\frac{\partial f}{\partial x} \right) & \frac{\partial}{\partial x} \left(\frac{\partial f}{\partial y} \right) \\ \frac{\partial}{\partial y} \left(\frac{\partial f}{\partial x} \right) & \frac{\partial}{\partial y} \left(\frac{\partial f}{\partial y} \right) \end{bmatrix}$

$$= \begin{bmatrix} \frac{\partial^{2}f}{\partial x^{2}} & \frac{\partial^{2}f}{\partial x^{2}y} \\ \frac{\partial^{2}f}{\partial y\partial x} & \frac{\partial^{2}f}{\partial y^{2}} \end{bmatrix} = \begin{bmatrix} f_{xx} & f_{yx} \\ f_{xy} & f_{yy} \end{bmatrix} = \begin{bmatrix} 42xy & 21x^{2} \\ 21x^{2} & 10y^{-3} \end{bmatrix}$$

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Smooth

Multimariable Functiona



Definition 5

f is kth order smooth if f and all partial derivatives up to order k exist and are continuous. We may say f is in the class of C^k functions.

No corners, edges, holes, cusps, jumps, singularities, etc.

Higher Order Derivatives

1. f_{xx} and f_{yy} are concavity E/W and N/S 2. Clairaut's Theorem (equality of mixed partials): $f_{xy} = f_{yx}$ if f is 2nd order "smooth" 3. $f_{xyx} = (f_{yx})_x = (f_{xy})_x = f_{xxy}$, etc. 4. $z = f(x, y) = 3x^2y + x(x - y)^7$ find $\nabla z|_{(2,1)}$ and $H_f(2,1)$; evaluated at (2,1)5. Compute all first and second order partials $f(x, y, z) = x^2 yz - 2zx + y^4 z^2.$ 6. PV = cT; find all second derivatives of P

Multivari

Partial Differential Equations



- 1. A function is called "harmonic" if it satisfies the Laplace equation $u_{xx} + u_{yy} = 0$. Show that $u = e^x \sin y$ is harmonic.
- 2. Show that $u = e^{-x} \sin(t x)$ satisfies the heat equation $u_t = k u_{xx}$.

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Example

Consider the surface of $f(x, y) = 16 - x^2 - y^2$.

1. Find slope in direction $\vec{v} = [2; 5]$.

$$D_{\vec{v}}f = \frac{[-2x, -2g] \cdot [2, 5]}{\sqrt{29}} = \frac{-4x - 10g}{\sqrt{29}}$$

- 2. Evaluate at (1,3) to get $D_{\vec{v}}f(1,3) = \frac{-34}{\sqrt{29}}$.
- 3. Find concavity.

$$D_{ec v}\left(rac{-4x-10y}{\sqrt{29}}
ight) = \left[rac{-4}{\sqrt{29}},rac{-10}{\sqrt{29}}
ight]\cdotrac{[2;5]}{\sqrt{29}} = -2$$

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Steepest Ascent



 $\overline{D}_{ec v}f = rac{\|
abla f\| \|ec v\| \cos heta}{\|ec v\|} = \|
abla f\| \cos heta.$

• steepest ascent direction $\theta = 0$, so $\vec{v} = \nabla f$

- ▶ steepest descent direction $-\nabla f$
- The steepest ascent slope is $\|\nabla f\|$.
- contour direction satisfies ∇f · v = 0, so ∇f is ⊥ to contours

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More Please

Sketch gradients at (1, 1), (1, 4), and (4, 1).







Suppose you are on a rolling hillside, and notice that "straight uphill" is 20° west of north, and that the slope in that direction is .18.

- 1. Find the gradient at your location.
- 2. Find the slope if you were to walk in the direction [3;4].
- 3. In which directions is the slope zero?
- 4. Draw a line splitting the plane into halves: uphill and downhill directions.

Concavity

Let $abla f = [f_x; f_y]$ and $H = egin{bmatrix} f_{xx} & f_{yx} \ f_{xy} & f_{yy} \end{bmatrix}$ be evaluated at a given point. Let $\vec{v} = [v_1; v_2]$ be velocity. slope $\overline{D_{ec v}f} = rac{1}{\|ec v\|}
abla f \cdot ec v = rac{1}{\|ec v\|} (v_1 f_x + v_2 f_y)$ concavity $D_{ec v}(D_{ec v}f) = rac{1}{\|v\|^2} egin{bmatrix} v_1 f_{xx} + v_2 f_{xy} \ v_1 f_{vx} + v_2 f_{vy} \end{bmatrix} \cdot egin{bmatrix} v_1 \ v_2 \end{bmatrix}$ $=rac{1}{v \cdot v}(v_1^2 f_{xx} + 2v_1 v_2 f_{xy} + v_2^2 f_{yy}) = v^T H v_1 v_2 f_{xy}$

Do a numerical example.

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Implicit Functions



Is it faith to understand nothing, and merely submit your convictions implicitly to the Church?

(John Calvin)

izquotes.com

When it's inconvenient to solve for a "dependent" variable, the graph defines a function implicitly. Sometimes expressed as solution set of F(x, y, z) = constant.

Implicit Differentiation

Suppose z is an implicit function of x and y. Then to find $\frac{\partial z}{\partial x}$, treat y as constant, but z as a function of x. Differentiate both sides w.r.t. x, and solve for $\frac{\partial z}{\partial x}$.

1.
$$x^2 + y^2 + z^2 = 121$$

find $\frac{\partial z}{\partial x}$ and $\frac{\partial z}{\partial y}$ at $(2, 6, 9)$.
2. If $z^3x = \ln(xyz)$, then find z_x and z_y .
3. find $\frac{\partial z}{\partial x}$ if $x(y^2z + e^{-z^2}) = 1$

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Derivatives

Gradient Field



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Derivatives

Continuity

$$f(x,y) = egin{cases} 1 & xy = 0 \ 0 & ext{otherwise} \end{cases}$$



1. Find ∇f . 2. Find $\lim_{x,y\to 0,0} f(x,y)$

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Black-Scholes

Call option price C(s, t). Today s = 540.

- ► *C* = 14.82
- $\blacktriangleright \quad \frac{\partial C}{\partial s} = 0.683 \text{ (delta)}$
- ▶ $\frac{\partial C}{\partial t} = -0.591$ (theta)

Estimate C tomorrow if s increases to 543.

Intermediate Variables

Let $z = f(x, y) = x^2 y$, with $x = t^3$ and $y = t^4$. 1. Substitute and find $\frac{dz}{dt}$. 2. Find ∇z , x'(t), and y'(t). 3. Check that $\frac{dz}{dt} = \frac{\partial z}{\partial x}\frac{dx}{dt} + \frac{\partial z}{\partial y}\frac{dy}{dt}$ There is one term for each intermediate variable. The derivative $\frac{dz}{dt}$ is the rate of change in z with respect to t, as x and y move parametrically.



Theorem 6

Suppose y is a function of \vec{u} , and \vec{u} is a function of \vec{x} . Then

$$rac{dy}{dec{x}} = rac{dy}{dec{u}}rac{dec{u}}{dec{x}}$$

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Chain Rule Pattern

A derivative is the rate of change of one variable with respect to another.

- Sketch input \rightarrow output layer network.
- Multiply derivatives that link the input to the output.
- Add terms, each one corresponding to a possible path of dependency.

Numerical Example



Given $\frac{dz}{d\vec{u}} = [5, 2, 4]$ and $\frac{d\vec{u}}{d\vec{x}} = \begin{bmatrix} 3 & -2 \\ 6 & 7 \\ -1 & 8 \end{bmatrix}$ 1. $\frac{dz}{dx_1} = (5)(3) + (2)(6) + (4)(-1) = 23$ Note this is a dot product. 2. All else equal, what happens to z if you turn the x_1 knob by .03? $\Delta z pprox dz = rac{dz}{dx_1} \Delta x_1 + rac{dz}{dx_2} \Delta x_2$

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Formula Example

$$z=(u+2v)^3,\ u=x^2y,\ v=e^xy$$

$$rac{dz}{dec{x}} = [3(u+2v)^2, \ 6(u+2v)^2] egin{bmatrix} 2xy & x^2 \ e^x y & e^x \end{bmatrix}$$

Expanded out,

 $\frac{\partial z}{\partial x} = \frac{\partial z}{\partial u}\frac{\partial u}{\partial x} + \frac{\partial z}{\partial v}\frac{\partial v}{\partial x} = 6y(u+2v)^2(x+e^x)$ $\frac{\partial z}{\partial y} = \frac{\partial z}{\partial u}\frac{\partial u}{\partial y} + \frac{\partial z}{\partial v}\frac{\partial v}{\partial y} = 3(u+2v)^2(x^2+2e^x)$

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Cash Flow

- Pops gives 5%, 7%, 10% of his income to Dad, Uncle, Aunt respectively.
- ▶ Dad gives 15% to you.
- ▶ Uncle gives 4% to you.
- ▶ Aunt gives 6% to you.



If Pops wins \$1000, how much will you (Y) get? Note the proportionality: $dY = \frac{dY}{dP}dP$

Voltage

V = IR (voltage, current, resistance).Find $\frac{dI}{dt}$ when P = 600 ohms, I = .04 amps $\frac{dR}{dt} = .5 \text{ (heating up)}$ $\frac{dV}{dt} = -.01 \text{ (battery draining)}$ $\frac{dV}{dt} = \frac{\partial V}{\partial I} \frac{dI}{dt} + \frac{\partial V}{\partial R} \frac{dR}{dt}$



BMI

A person that weighs w kg and is h cm tall has a body mass index of

 $B = w(h/100)^{-2}$

A boy currently 140 cm tall weighs 33 kg. He is growing at 0.6 cm/month and 0.4 kg/month. Find the rate of change in his BMI.

From Polar

Let $f(x, y) = \frac{y}{x^2+1}$. Using the polar change of variables, find $\frac{\partial f}{\partial r}$ and $\frac{\partial f}{\partial \theta}$.

$\frac{\partial f}{\partial r} =$	$\frac{\partial f}{\partial x} \frac{\partial x}{\partial r}$	+	$\frac{\partial f}{\partial y} \frac{\partial y}{\partial r}$	_	$rac{-2xy\cos heta}{(x^2+1)^2}$	+	$\frac{\sin\theta}{x^2+1}$
$\frac{\partial f}{\partial \theta} =$	$\frac{\partial f}{\partial x} \frac{\partial x}{\partial \theta}$	+	$\frac{\partial f}{\partial y}\frac{\partial y}{\partial \theta}$		$rac{2xyr\sin heta}{(x^2+1)^2}$.	+	$rac{r\cos\theta}{x^2+1}$

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Optimization

Temperature

Suppose temperature is given by

$$T(x,y) = \exp\left(\frac{12xy-x^2-y^4}{50}\right)$$

degrees K. Find the extreme temperature(s).

 At an extreme, no improvement in any direction.

 $rg \max x, y T(x,y) = rg \max x, y(12xy - x^2 - y)$





Extrema

Let $f: D \to \mathbb{R}$, where $D \subseteq \mathbb{R}^n$.

Definition 7

 $f(\vec{x}_0)$ is a local maximum if $\exists \epsilon > 0$ such that $f(\vec{x}) \leq f(\vec{x}_0)$ whenever $\|\vec{x} - \vec{x}_0\| < \epsilon$

 $f(\vec{x}_0)$ is a global (absolute) maximum if $f(\vec{x}) \leq f(\vec{x}_0)$ for all $\vec{x} \in D$

local/global minimum defined similarly

 maximums and minimums are collectively called extrema

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Searching for Extrema

Definition 8

The point \vec{x}_0 is a critical point if $\nabla f(\vec{x}_0) = \vec{0}$, or if the gradient is not defined.

Theorem 9 (Fermat's Theorem)

Extrema can exist only at critical points or on the boundry of the domain D.

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Saddle Points

Definition 10

A saddle point is a critical pt having both higher and lower function values arbitrarily close by.

Contours look like concentric ellipses at extrema, and hyperbolas at saddles.



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2nd Derivative Test

Theorem 11 (2nd Derivative Test) Suppose $\nabla f(a, b) = \vec{0}$, and f is locally smooth enough. Let $\overline{D} = egin{bmatrix} f_{xx} & f_{xy} \ f_{yx} & f_{yy} \end{bmatrix} = f_{xx}f_{yy} - f_{xy}^2$ ▶ D > 0, $f_{xx} > 0$ implies f(a, b) is local min. ▶ D > 0, $f_{xx} < 0$ implies f(a, b) is local max. \blacktriangleright D < 0 implies f(a, b) is a saddle. ▶ If D = 0, the test is inconclusive.

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Local Concavity

Justify the 2nd deriv. test:

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Optimization

Examples

Use the gradient and Hessian to find and classify all critical points of the objective function.

1.
$$z = 4 + x^3 + y^3 - 3xy$$

2. $z = \frac{x^3}{3} + \frac{4y^3}{3} - x^2 - 3x - 4y - 3$
(visualize in Maxima)

- 3. mvopt-apps.pdf #5
- 4. Find shortest distance from point to plane.

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Best Fit Line

Find the line y = a + bx that has least squares error in fitting the points:

 $\{(0, 15), (3, 24), (5, 32), (9, 50)\}$

The objective function is $f(a, b) = (a - 15)^2 + (a + 3b - 25)^2 + (a + 5b - 33)^2 + (a + 9b - 48)^2$.

General formula for a and b given $\{(x_i, y_i)_{i=1}^n\}$?





Optimization

Not In Kansas Anymore



Find and classify the critical points of

$$f(x,y) = (x^2 - 1)^2 + (x^2 - e^y)^2$$

Notice anything weird?



Global/Absolute Extrema

- The extreme value theorem guarantees that a continuous function attains its minimum and maximum on a closed and bounded domain.
- Candiate locations for global extrema are critical points and boundary points.
- On the boundary, substitute and find 1 variable critical pts; check corners.
- Evaluate the objective function at each candidate and select the highest and lowest.

Optimization

Examples

- 1. A flat circular plate covers $x^2 + y^2 \leq 1$. The temperature at a given point on the plate is $T(x, y) = x^2 + 3y^2 x$. Find the hottest and coldest points on the plate.
- 2. Let $f(x, y) = 2x^2 4x + y^2 4y + 1$ be defined on the triangle bounded by x = 0, y = 3, and y = x. List all points where an absolute extremum may occur, and evaluate f at each one.

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Constrained Optimization



Optimize objective function $f(x, y) = x^2 + 2y^2$ subject to (s.t.) the constraint $y = x^2 - 4$.

- Draw the contours of f, along with the constraint path.
- ▶ substitution method: plug $x^2 = y + 4$ into f and make it a calc I problem in $y \in [-4, \infty)$
- note that you are changing elevation as you cross contours, so at extrema the contours must be parallel to the path.

Lagrange Optimization

- Constraint is a contour of the surface $g(x, y) = y x^2 + 4$.
- At extrema, the gradient directions of f and g must coincide.
- Lagrange system of equations:
 ∇f = λ∇g g(x, y) = 0



- ► λ is the Lagrange multiplier
- solve eqns and evaluate objective func. to find potential extrema (Maxima)

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Milkmaid Problem

The problem is described [here]. In particular, suppose

- The maid is at (-1, 0).
- The cow is at (1,0).
- The objective function is $f(x, y) = \sqrt{(x+1)^2 + y^2} + \sqrt{(x-1)^2 + y^2}$, which has elliptical contours.
- The river's course is described by $(x^2 + 3y 6)(y 2) = 3x$.



Optimization



Find the point on the curve $x^2 + xy = 1$ closest to the origin.

$$\min x^2 + y^2$$

s.t. $x^2 + xy - 1 = 0$

Show that (.841, .348) satisfies the Lagrange equations.

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Example

Find the volume of the largest rectangular box, having sides parallel to coordinate planes, and inscribed in the ellipsoid $16x^2 + 4y^2 + 9z^2 = 144$.

- label one corner (x, y, z), so the objective function is V(x, y, z) = 8xyz
- the constraint is g(x, y, z) = 16x² + 4y² + 9z² - 144
 Lagrange system of equations:

Bagrange system of equation

$$8yz = \lambda(32x)$$

 $8xz = \lambda(8y)$
 $8xy = \lambda(18z)$
 $16x^2 + 4y^2 + 9z^2 - 144 = 0$

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Optimization Summary

The objective function f expresses the quantity you want maximized or minimized. Identify independent variables. Note the feasible region, including potential constraint g = 0.

- Unbounded domain: local extrema occur at critical pts; classify using 2nd D. test
- Bounded domain: also check boundary and corners; evaluate f to select global extrema
- Constrained: solve Lagrange equations for potential extrema
Optimization

Example

Optimize $z = x^3 + y^3 + (x-2)^2 + (y-5)^2$ on the region bdb y = 0 and $y = 4 - x^2$.

- 1. Use Maxima to graph on $[-4, 4] \times [4, 4]$.
- 2. Find and classify interior critical points.
- 3. Solve the Lagrange eqns in Maxima for parabolic boundary.
- 4. Find the absolute extrema.

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